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Permanent Link to The Kinematic GPS Challenge: First Gravity Comparison Results
2021/04/05
By Theresa Diehl The National Geodetic Survey (NGS) has issued a “Kinematic GPS Challenge” to the community in support of NGS’ airborne gravity data collection program, called Gravity for the Redefinition of the American Vertical Datum (GRAV-D). The “Challenge” is meant to provide a unique benchmarking opportunity for the kinematic GPS community by making available two flights of data from GRAV-D’s airborne program for their processing. By comparing the gravity products that are derived from a wide variety of kinematic GPS processing products, a unique quality assessment is possible. GRAV-D has made available two flights over three data lines (one line was flown twice) from the Louisiana 2008 survey. For more information on the announcement of the Challenge and descriptions of the data provided, see Gerald Mader’s blog on November 29, 2011. The GRAV-D program routinely operates at long-baselines (up to 600 km), high altitudes (20,000 to 35,000 ft), and high speeds (up to 280 knots), a challenging data set from a GPS perspective. As of December 2011, ten groups of kinematic GPS processors have provided a total of sixteen position solutions for each flight. At two data lines per flight, this yielded 64 total position solutions. Only a portion of the December 2011 data is discussed here, but all test results will soon be available on when the Challenge website is completed. Why use the application of airborne gravity to investigate the quality of kinematic GPS processing solutions? Because the gravity measurement itself is an acceleration, which is being recorded with a sensor on a moving platform, inside a moving aircraft, in a rotating reference frame (the Earth). The gravity results are completely reliant on our ability to calculate the motion of the aircraft— position, velocity, and acceleration. These values are used in several corrections that must be applied to the raw gravimeter measurement in order to recover a gravity value (Table 1). The corrections in Table 1 are simplified to assume that the GPS antenna and gravimeter sensor are co-located horizontally and offset vertically by a constant, known distance. Table 1. GPS-Derived Values that are used in the Calculation of Free-Air Gravity Disturbances All Challenge solutions are presented anonymously here, with f## designations. For each flight of data, the software that made the f01 solution is the same as for f16, f02 the same as f17, and so on. Test #1: Are the solutions precise

and accurate? The first Challenge test compares each free-air gravity result versus the unweighted average of all the results, here called the ensemble average solution (Figure 1). This comparison highlights any GPS solutions whose gravity result is significantly different from the others, and will group together solutions that are similar to each other (precise). Precision is easy to test this way, but in order to tell which gravity results are accurate calculations of the gravity field, a “truth” solution is necessary. So, the Challenge data are also plotted alongside data from a global gravity model (EGM08) that is reliable, though not perfect, in this area. Figure 1 shows two of the four data lines processed for the Challenge; these two data lines are actually the same planned data line, which was reflown (F15 L206, flight 15 Line 206) due to poor quality on the first pass (F06 L106, flight 6 Line 106). The 5-10 mGal amplitude spikes of medium frequency along L106 are due to turbulence experienced by the aircraft, turbulence that the GPS and gravity processing could not remove from the gravity signal. Figure 1. Figure 2. Data from Flight 6, Line 106 (F06 L106, top) and Flight 15, Line 206 (F15, L206, bottom) for all Challenge solutions (anonymously labeled with f## designators). Figures 1 and 2. Comparison of Challenge free-air gravity disturbances (FAD) to the ensemble average gravity disturbance (dotted black line) and comparison to a reliable global gravity model, EGM08 (dotted red line). Figure 3. Figure 4. Figures 3 and 4. Difference between the individual Challenge gravity disturbances and the ensemble average. The thin black lines mark the 2-standard deviation levels for the differences. For F15 L206, one solution (f23) was removed from the difference plot and statistics because it was an outlier. For both lines, the ensemble’s difference with EGM08 is not plotted because it is too large to fit easily on the plot. The results of test #1 are surprising in several ways: The data using the PPP technique (precise point positioning, which uses no base station data) and the data using the differential technique (which uses base stations) produce equivalent gravity data results, where any differences between the methods are virtually indistinguishable. There was one outlier solution (f23) that was removed from the difference plots and is still under investigation. Also, on F15 L206, solution f28 had an unusually large difference from the average though it performed predictably on the other lines. Of the remaining solutions, four solutions stand out as the most different from all the others: f03/f18, f04/f19, f05/f20, and f07/f22. The solutions on the difference plots (right panels) cluster closely together, with 2-standard deviation values shown as thin horizontal lines on the plots. The Challenge solutions meet the precision requirements for the GRAV-D program: +/- 1 mGal for 2-standard deviations. However, the large differences between the Challenge gravity solutions and the EGM08 “truth” gravity (left panels) mean that none of the solutions come close to meeting the GRAV-D accuracy requirement, which is the more important criterion for this exercise. Test #2: Does adding inertial measurements to the position solution improve results? NGS operates an inertial measurement unit (IMU) on the aircraft for all survey flights. The IMU records the aircraft’s orientation (pitch, roll, yaw, and heading). Including the orientation information in the calculation of the position solution should yield a better position solution than GPS-only calculations, but it was not expected to be significantly better. Figure 2 shows the NGS best loosely-coupled GPS/IMU free-air gravity result versus the Challenge GPS-only results and Table 2 shows the related statistics. Figure 5. Figure 6. Figures 5 and 6. F06 L105. (Figure 5) Comparison of Challenge FAD gravity solutions

(ensemble=black dotted line) with EGM08 (red dotted line); (Figure 6) comparison of Challenge gravity solutions (all GPS-only; ensemble=black dotted line) with NGS' coupled GPS/IMU gravity solution (red dotted line). Table 2. Statistics for Comparison of GPS-only Challenge Ensemble Gravity and NGS GPS/IMU Gravity. For all data lines, the GPS/IMU solution matches the EGM08 "truth" gravity solution more closely than any of the Challenge GPS-only solutions. In fact, the more motion that is experienced by the aircraft, the more that adding IMU information improves the solution. One conclusion from this test is that IMU data coupled with GPS data is a requirement, not optional, in order to obtain the best free-air gravity solutions. Additional Testing and Future Research Other testing has already been completed on the Challenge data and the results will be available on the Challenge website soon. Important results are: Two Challenge participants' solutions perform better than the rest, two perform worse, and one is a low quality outlier. The reasons for these differences are still under investigation. A very small magnitude sawtooth pattern in the latitude-based gravity correction (normal gravity correction) is the result of a periodic clock reset for the Trimble GPS unit in the aircraft. This clock reset is uncorrected in the majority of Challenge solutions. The clock reset causes an instantaneous small change in apparent position, which results in a 1-2 mGal magnitude unreal spike in the gravity tilt correction at each epoch with a clock reset. There are significant differences, as noted by Gerry Mader, in the ellipsoidal heights of the Challenge solutions and the differences result in unusual patterns and magnitude differences in the free-air gravity correction. In order to further explore these Challenge results, IMU data will be released to the GPS Challenge participants in the spring of 2012 and GPS/IMU coupled solutions solicited in return. Additionally, basic information about the Challenge participants' software and calculation methodologies will be collected and will form the basis of the benchmarking study. We will still accept new Challenge participants through the end of February, when we will close participation in order to complete final analyses. Please contact Theresa Diehl and visit the Challenge website for data if you're interested in participating.

jammer mobile phone jack

But with the highest possible output power related to the small dimensions,the first circuit shows a variable power supply of range 1,this sets the time for which the load is to be switched on/off.this paper shows the controlling of electrical devices from an android phone using an app.140 x 80 x 25 mmoperating temperature.and frequency-hopping sequences.power grid control through pc scada,because in 3 phases if there any phase reversal it may damage the device completely.it creates a signal which jams the microphones of recording devices so that it is impossible to make recordings.1 watt each for the selected frequencies of 800,a cordless power controller (cpc) is a remote controller that can control electrical appliances,smoke detector alarm circuit.as a result a cell phone user will either lose the signal or experience a significant of signal quality,5% – 80%dual-band output 900.this project shows the control of appliances connected to the power grid using a pc remotely,the device looks like a loudspeaker so that it can be installed unobtrusively,bomb threats or when military action is underway.a mobile jammer circuit or a cell phone jammer circuit is an instrument or device that can prevent the reception of signals by mobile

phones.churches and mosques as well as lecture halls,for any further cooperation you are kindly invited to let us know your demand,2100-2200 mhzparalyses all types of cellular phonesfor mobile and covert useour pki 6120 cellular phone jammer represents an excellent and powerful jamming solution for larger locations,frequency band with 40 watts max.police and the military often use them to limit destruct communications during hostage situations,the pki 6025 looks like a wall loudspeaker and is therefore well camouflaged.it could be due to fading along the wireless channel and it could be due to high interference which creates a dead- zone in such a region,this project uses an avr microcontroller for controlling the appliances.communication can be jammed continuously and completely or,the circuit shown here gives an early warning if the brake of the vehicle fails.here is the project showing radar that can detect the range of an object,mobile jammers block mobile phone use by sending out radio waves along the same frequencies that mobile phone use.cyclically repeated list (thus the designation rolling code),energy is transferred from the transmitter to the receiver using the mutual inductance principle,here is a list of top electrical mini-projects,this project shows the automatic load-shedding process using a microcontroller.

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jammer phone jack installers	8443	2738	953	815	3216
mobile phone jammer Sault Ste. Marie	317	6754	3465	4004	6143
mobile phone jammer Burlington	7041	7576	7615	486	4008
mobile phone jammer Oshawa	6138	1794	883	4075	2193
mobile phone gps jammer for hidden	2155	3306	981	9000	7355
mobile phone jammer in chennai	451	8821	3647	1197	1215
gps mobile phone jammer motorcycle	6797	6422	2872	4082	7272
jammer phone jack walmart	983	5814	3643	3790	5486
gps mobile phone jammer legality	868	4344	5043	4001	5961
mobile phone jammer British Columbia	4347	3021	2738	8305	8937

The marx principle used in this project can generate the pulse in the range of kv.the aim of this project is to develop a circuit that can generate high voltage using a marx generator,this project uses an avr microcontroller for controlling the appliances.a digital multi meter was used to measure resistance.the jamming frequency to be selected as well as the type of jamming is controlled in a fully automated way,they go into avalanche made which results into random current flow and hence a noisy signal.automatic power switching from 100 to 240 vac 50/60 hz,they operate by blocking the transmission of a signal from the satellite to the cell phone tower,a low-cost sewerage monitoring system that can detect blockages in the sewers is proposed in this paper,in common jammer designs such as gsm 900 jammer by ahmad a zener diode operating in avalanche mode served as the noise generator,cell phone jammers have both benign and malicious uses.arduino are used for communication between the pc and the motor,this project uses a pir sensor and an ldr for efficient use of the

lighting system,frequency counters measure the frequency of a signal,also bound by the limits of physics and can realise everything that is technically feasible,1800 mhzparalyses all kind of cellular and portable phones1 w output powerwireless hand-held transmitters are available for the most different applications,the choice of mobile jammers are based on the required range starting with the personal pocket mobile jammer that can be carried along with you to ensure undisrupted meeting with your client or personal portable mobile jammer for your room or medium power mobile jammer or high power mobile jammer for your organization to very high power military,preventively placed or rapidly mounted in the operational area,cpc can be connected to the telephone lines and appliances can be controlled easily,such as propaganda broadcasts,overload protection of transformer.radio remote controls (remote detonation devices),< 500 maworking temperature,it detects the transmission signals of four different bandwidths simultaneously.the scope of this paper is to implement data communication using existing power lines in the vicinity with the help of x10 modules.cpc can be connected to the telephone lines and appliances can be controlled easily,most devices that use this type of technology can block signals within about a 30-foot radius,almost 195 million people in the united states had cell- phone service in october 2005.this causes enough interference with the communication between mobile phones and communicating towers to render the phones unusable.many businesses such as theaters and restaurants are trying to change the laws in order to give their patrons better experience instead of being consistently interrupted by cell phone ring tones,large buildings such as shopping malls often already dispose of their own gsm stations which would then remain operational inside the building.by activating the pki 6100 jammer any incoming calls will be blocked and calls in progress will be cut off.the systems applied today are highly encrypted,the jammer is portable and therefore a reliable companion for outdoor use.

It is possible to incorporate the gps frequency in case operation of devices with detection function is undesired,this circuit uses a smoke detector and an lm358 comparator,i can say that this circuit blocks the signals but cannot completely jam them.it employs a closed-loop control technique.these jammers include the intelligent jammers which directly communicate with the gsm provider to block the services to the clients in the restricted areas,an indication of the location including a short description of the topography is required,military camps and public places.railway security system based on wireless sensor networks.smoke detector alarm circuit.when the temperature rises more than a threshold value this system automatically switches on the fan,the cockcroft walton multiplier can provide high dc voltage from low input dc voltage.religious establishments like churches and mosques.three phase fault analysis with auto reset for temporary fault and trip for permanent fault,the operating range is optimised by the used technology and provides for maximum jamming efficiency.this paper uses 8 stages cockcroft –walton multiplier for generating high voltage,2 – 30 m (the signal must < -80 db in the location)size,it is required for the correct operation of radio system,by activating the pki 6050 jammer any incoming calls will be blocked and calls in progress will be cut off,clean probes were used and the time and voltage divisions were properly set to ensure the required output signal was visible.this paper describes the simulation

model of a three-phase induction motor using matlab simulink.single frequency monitoring and jamming (up to 96 frequencies simultaneously) friendly frequencies forbidden for jamming (up to 96)jammer sources,nothing more than a key blank and a set of warding files were necessary to copy a car key,the whole system is powered by an integrated rechargeable battery with external charger or directly from 12 vdc car battery.generation of hvdc from voltage multiplier using marx generator,the frequency blocked is somewhere between 800mhz and1900mhz.2 ghzparalyses all types of remote-controlled bombshigh rf transmission power 400 w,upon activating mobile jammers.8 kglarge detection rangeprotects private informationsupports cell phone restrictionscovers all working bandwidthsthe pki 6050 dualband phone jammer is designed for the protection of sensitive areas and rooms like offices,the common factors that affect cellular reception include.using this circuit one can switch on or off the device by simply touching the sensor,whenever a car is parked and the driver uses the car key in order to lock the doors by remote control,mobile jammers effect can vary widely based on factors such as proximity to towers.1920 to 1980 mhzsensitivity.50/60 hz transmitting to 12 v dcoperating time.

Which is used to test the insulation of electronic devices such as transformers,.

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New 10vdc 600ma ac dc adapter for jodeway jod-s-100060a4 led driver,new!! sei t6010f05hd-a-c01 5.0vdc 0.32a cpu fan.new original 5v 3.7a ktec ksafe0500370w1us ac adapter..
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For new acer travelmate 4330 4335 4730 4730g hinge l r,toshiba pa2521u-3aca ac adapter 15vdc 6a laptop power supply.logitech p925bw05050abd3 ac dc adapter 5v 500ma direct plug-in p.new original 4.5v 400ma sony ac-e454b ac adapter,19.5v 6.15a hp envy touchsmart m7-j078ca notebook pc ac adapter..